

Special theory of relativity ①

Newton's laws invariant under Galilean transformations

If Newton's laws hold in some frame of reference, they will hold in another frame of reference defined by the transformations

$$\vec{r}' = \vec{r} - \vec{v}t$$

$$t' = t$$

Primed frame has uniform velocity \vec{v} as seen from unprimed frame

Wave equation not invariant under Galilean transformations

$$\text{Let } \vec{v} = v \hat{z}$$

$$\nabla^2 \psi - \frac{1}{c^2} \frac{\partial^2 \psi}{\partial t^2} = 0.$$

$$\rightarrow \left[\nabla'^2 - \frac{1}{c^2} \frac{\partial^2}{\partial t'^2} - \frac{2}{c^2} \vec{v} \cdot \vec{\nabla}' \frac{\partial}{\partial t'} - \frac{1}{c^2} (\vec{v} \cdot \vec{\nabla}')^2 \right] \psi' = 0$$

No "simple" (kinematic) transformation on ψ to restore invariance.

Postulates of relativity

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- 1) Laws of nature and results of experiments in a frame of reference invariant under uniform translation of the frame
- 2) Speed of light is independent of the motion of its source
- 2') Universal limiting speed c .

Linear transformations

Assume that two frames have relative velocity $\vec{v} = v \hat{x}$

$$x' = A(v)x + B(v)t$$

$$t' = C(v)x + D(v)t$$

Limiting universal speed $c \Rightarrow$

$$\left[\frac{dx'}{dt'} = \pm c \Leftrightarrow \frac{dx}{dt} = \pm c \right]$$

$$\Rightarrow \alpha(v) [c^2 dt^2 - dx^2] = c^2 (dt')^2 - (dx')^2$$

primed \longleftrightarrow unprimed

$$\Rightarrow \alpha(v) = \frac{1}{\alpha(-v)}$$

Further isotropy $\Rightarrow \alpha(u) = \alpha(-u)$

$$\Rightarrow \alpha(u)^2 = 1 \text{ or } \alpha(u) = \pm 1$$

$$c^2(dt')^2 - (dx')^2 = \pm [c^2 dt^2 - dx^2]$$

$$dx' = 0 \Rightarrow \frac{dx}{dt} = u$$

$$(dt')^2 = \pm \frac{1}{c^2} [c^2 - u^2] (dt)^2$$

$u < c \Rightarrow +$ sign has to be chosen

so that t and t' remain real

$$(dt')^2 = \left(1 - \frac{u^2}{c^2}\right) (dt)^2$$

$$dt = \frac{dt'}{\sqrt{1 - \frac{u^2}{c^2}}} \quad \left(+ \text{ sign so that } dt = dt' \text{ when } u \rightarrow 0 \right)$$

$$dx = u \frac{dt'}{\sqrt{1 - \frac{u^2}{c^2}}}$$

$$\Rightarrow t = \gamma [t' + f(x')] \quad \gamma = \frac{1}{\sqrt{1 - \frac{u^2}{c^2}}}$$

$$x = \gamma [ut' + g(x')]$$

$$\frac{dx}{dt} = c = \frac{u + g' \frac{dx'}{dt'}}{1 + f' \frac{dx'}{dt'}} = \frac{u + g'c}{1 + f'c}$$

$$\therefore \frac{dx'}{dt'} = c$$

$$\Rightarrow v + g'c = c + f'c^2$$

$$\Leftrightarrow g' = 1 - \frac{v}{c} + f'c$$

$$dt' = 0$$

$$\Rightarrow dx = \gamma g' dx'$$

$$dt = \gamma f' dx'$$

$$\gamma^2 (dx')^2 [c^2 (f')^2 - (g')^2] = -(dx')^2$$

$$\Leftrightarrow g'^2 - c^2 (f')^2 = \frac{1}{\gamma^2}$$

$$g' + cf' = \frac{1}{\gamma^2} \frac{1}{1 - v/c} = 1 + v/c$$

$$g' - cf' = 1 - v/c$$

$$g' = 1; \quad f' = v/c^2$$

$$\text{If } (x', t') = (0, 0) \Rightarrow (t, x) = (0, 0)$$

$$t = \gamma \left(t' + \frac{v x'}{c^2} \right)$$

$$x = \gamma (v t' + x')$$

$$\Rightarrow x' = \gamma (x - vt)$$

$$t' = \gamma \left(t - \frac{vx}{c^2} \right)$$

Lorentz transformations

$$\beta = v/c$$

$$\gamma = \frac{1}{\sqrt{1 - \frac{v^2}{c^2}}}$$

$$x_0 = ct$$

$$\vec{x} = (x_1, x_2, x_3)$$

$$x'_0 = \gamma (x_0 - \vec{\beta} \cdot \vec{x})$$

$$\vec{x}' = \vec{x} + \frac{\gamma - 1}{\beta^2} (\vec{\beta} \cdot \vec{x}) \vec{\beta} - \gamma \beta x_0$$

$$\vec{\beta} = \frac{\vec{v}}{c}$$

$$\beta = \tanh \rho \quad [\beta \in [0, 1]]$$

$$[\gamma \in [0, \infty]]$$

$$\gamma = \cosh \rho$$

$$x'_0 = x_0 \cosh \rho - x_1 \sinh \rho$$

$$x'_1 = -x_0 \sinh \rho + x_1 \cosh \rho$$

Like rotation matrix but \cosh & \sinh
in place of \cos and \sin

$x_0 \rightarrow ix_0$ and $v \rightarrow iv$ restores \cos & \sin

Four vector

$$A'_0 = \gamma (A_0 - \vec{\beta} \cdot \vec{A})$$

$$A'_{11} = \gamma (A_{11} - \beta A_0)$$

$$A'_\perp = A_\perp$$

$$(A'_0)^2 - |\vec{A}'|^2 = A_0^2 - |\vec{A}|^2$$

Scalar product

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$$A'_0 B'_0 - \vec{A}' \cdot \vec{B}' = A_0 B_0 - \vec{A} \cdot \vec{B}$$

preserved by Lorentz transformations

$$\lambda'^{\alpha} = \lambda'^{\alpha} (\xi^{\lambda^{\beta}} \xi) \quad (\alpha, \beta = 0, 1, 2, 3)$$

Lorentz scalar unchanged by Lorentz transformations

Contravariant vector

$$A'^{\alpha} = \frac{\partial \lambda'^{\alpha}}{\partial \lambda^{\beta}} A^{\beta}$$

Covariant vector

$$B'_{\alpha} = \frac{\partial \lambda^{\beta}}{\partial \lambda'^{\alpha}} A_{\beta}$$

Contravariant tensor of rank R

$$F'^{\alpha\beta} = \frac{\partial \lambda'^{\alpha}}{\partial \lambda^{\gamma}} \frac{\partial \lambda'^{\beta}}{\partial \lambda^{\delta}} F^{\gamma\delta}$$

Covariant tensor of rank R

$$G'_{\alpha\beta} = \frac{\partial \lambda^{\gamma}}{\partial \lambda'^{\alpha}} \frac{\partial \lambda^{\delta}}{\partial \lambda'^{\beta}} G_{\gamma\delta}$$

Mixed tensor of rank R

$$H'^{\alpha}_{\beta} = \frac{\partial \lambda'^{\alpha}}{\partial \lambda^{\gamma}} \frac{\partial \lambda^{\delta}}{\partial \lambda'^{\beta}} H^{\gamma}_{\delta}$$