Numerical Implementation of Anisotropic Diffusion

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Outline

- anisotropic diffusion eq. quite common: image processing, transport in magnetized plasmas, etc.
- finite difference scheme
- monotonicity & extremum principle
- limiters (minmod, van Leer)
- stability timestep & semi-implicit approach
- super-time-stepping

Diffusion in image processing



aims:

 maintain sharp edges
 no spurious edges at low resolution
 maximum detail with minimum storage

Diffusion in image processing

 $\frac{\partial}{\partial t}I(x,y,t) = c\nabla^2 I(x,y,t)$ isotropic constant diffusion for intensity

$$I_{\vec{k}}(t) = I_{\vec{k}}(0) \exp(-ck^2 t)$$

Fourier space: larger k modes damped more a low pass filter

$$G_{\sigma} \star I^0(\vec{x}) = \int G_{\sigma}(\vec{x} - \vec{x}') I^0(\vec{x}') d\vec{x}'$$

image convolved with a kernel

$$\widehat{G_{\sigma} \star I^0}(\vec{k}) = \widehat{G_{\sigma}}(\vec{k})\widehat{I^0}(\vec{k})$$

convolution theorem

$$G_{\sigma}(\vec{x}) = \frac{1}{(2ct)^{d/2}} \exp\left(-\frac{\vec{x} \cdot \vec{x}}{4ct}\right)$$

isotropic diffusion equivalent to isotropic Gaussian smoothing Kernel in real space

AD in image processing

$$\frac{\partial}{\partial t}I(x,y,t) = \vec{\nabla} \cdot (c(x,y,t)\vec{\nabla}I)$$

more general diffusion equation Perona-Malik 1990

$$c\left(||\nabla I||\right) = e^{-(||\nabla I||/K)^2}$$
$$c\left(||\nabla I||\right) = \frac{1}{1 + \left(\frac{||\nabla I||}{K}\right)^2}$$

 \cap

nonlinear diffusion equation larger diffusion where I(x,y) is smooth smaller where sharp changes in I (edges)

works quite well in practice mathematical issues: ill-posed, regularization noisy images can have spurious large gradients! these must be smoothened

Diffusion in image processing



AD indeed produces better results

Plasma Thermal Conductivity

diffusivity (cm²s⁻¹) \mathbf{x} : v_t x mfp; mfp~1/(n σ); σ ~b² ln Λ ; b~e²/kT

diffusivity ~ T^{5/2}/n; e-s conduct heat as they are 40 times faster than protons

$$nT\frac{ds}{dt} = -\nabla \cdot \mathbf{Q} \qquad s = \frac{k_B}{\gamma - 1} \ln\left(\frac{p}{\rho^{\gamma}}\right) \quad \text{entropy}$$

Plasma Thermal Conductivity a tricky issue!

 $\mathbf{Q} = -\kappa \nabla T = -\chi n k_B \nabla T$ for unmagnetized plasma

$\mathbf{Q} = -\kappa \hat{b} \nabla_{\parallel} T = -\kappa \hat{b} (\hat{b} \cdot \nabla) T$ for magnetized plasma



particles move along B w. small Larmor radii but diffuse along B with a path length of mfp; mfp>> p_{L}

$$D_{\parallel}\sim v_t^2/
u\gg D_{\perp}\sim
ho_L^2
u$$
 true for all transport coeffts.

All this is fine for a given B, but B changes because of plasma currents, small scale instabilities! Observed perp. transport is enhanced. This is the key problem of tokamaks.



Buoyancy instabilities

buoyant response of gravitationally stratified fluids with anisotropic conduction fundamentally different from adiabatic fluids

MTI: makes field line vertical [McCourt et al. 2011]



HBI: makes field lines horizontal





Numerical implementation



$$\frac{\partial T}{\partial t} = -\nabla \cdot \mathbf{Q} = \nabla \cdot (\chi \hat{b} \hat{b} \cdot \nabla T)$$

 $\mathbf{Q} = -\chi \hat{b} \nabla_{\parallel} T$

with constant $\pmb{\varkappa}$

$$Q_x = -\chi b_x \left(b_x \frac{\partial T}{\partial x} + b_y \frac{\partial T}{\partial y} \right) \quad Q_y = -\chi b_y \left(b_x \frac{\partial T}{\partial x} + b_y \frac{\partial T}{\partial y} \right)$$
$$\frac{T_{i,j}^{n+1} - T_{i,j}^n}{\Delta t} = -\frac{Q_{x,i+1/2,j} - Q_{x,i-1/2,j}}{\Delta x} - \frac{Q_{y,i,j+1/2} - Q_{y,i,j-1/2}}{\Delta y}$$

$$Q_{x,i+1/2,j} = -\chi b_x \left(b_x \frac{T_{i+1,j} - T_{i,j}}{\Delta x} + b_y \frac{\partial T}{\partial y} \right)$$

conservative differencing s.t., internal fluxes cancel

needs to be interpolated at (i+1/2,j)

Centered Differencing



Problem w. CD

its not monotonicity preserving! can give -ve temperatures!



Problem w. CD

its not extrema preserving! can give -ve temperatures!

gradients gives non-monotonicity!

Solution?

normal terms:
$$Q_{x,N} = -b_x^2 \frac{\partial T}{\partial x}, Q_{y,N} = -b_y^2 \frac{\partial T}{\partial y}$$
 flux always down the gradient

transverse terms:
$$Q_{x,T} = -b_x b_y \overline{\frac{\partial T}{\partial y}}, Q_{y,T} = -b_x b_y \overline{\frac{\partial T}{\partial x}}$$

- can have any sign!

$$\overline{\frac{\partial T}{\partial y}} = \mathcal{L}\left(\left.\frac{\partial T}{\partial y}\right|_{i+1,j+1/2}, \left.\frac{\partial T}{\partial y}\right|_{i,j+1/2}, \left.\frac{\partial T}{\partial y}\right|_{i+1,j-1/2}, \left.\frac{\partial T}{\partial y}\right|_{i,j-1/2}\right)$$

choosing arithmetic averaging does not work! can be arbitrarily large and of any sign

need to have a better interpolation which is not affected by a large +/value of the argument

Minmod limiter

minmod(a,b)=0 if ab <=0, min(a,b) if ab > 0

smoother, higher order accuracy, still nonlinear

van Leer(a,b)=0 if ab <=0, 2ab/(a+b) if ab > 0

limited averaging which vanishes if all 4 arguments don't have the same sign

non-monotonic even at late times

Negative temperature!

with large temperature gradients

negative temperature => sound wave becomes unstable =>code blows up

large temperature gradients are natural in plasmas; e.g., solar prominences in corona, 3 phases of the ISM

our method is essential for simulating such plasmas robustly from first principles

Another problem

the scheme is explicit and governed by a stability CFL constraint

 $\Delta t < \frac{\Delta x^2}{2}$

$$-2\chi$$
 for high conductivity plasma such as ICM, this can be 1000s time smaller than $\frac{\Delta x}{c_s}$

one can subcycle: for every hydro timestep apply many conduction cycles but this is slow; better to go implicit where there is no stability constraint

$$\frac{T_{ij}^{\star} - T_{ij}^{n}}{\chi_{\parallel}\Delta t} = b_{x,i+1/2j}^{2} \frac{T_{i+1,j}^{\star} - T_{ij}^{\star}}{\Delta x^{2}} - b_{x,i-1/2j}^{2} \frac{T_{i,j}^{\star} - T_{i-1,j}^{\star}}{\Delta x^{2}} + \frac{b_{x,i+1/2j}b_{y,i+1/2,j}}{\Delta x\Delta y} \overline{\Delta T}_{i+1/2,j}^{n} - \frac{b_{x,i-1/2,j}b_{y,i-1/2,j}}{\Delta x\Delta y} \overline{\Delta T}_{i-1/2,j}^{n},$$

$$\frac{T_{i,j}^{n+1} - T_{i,j}^{\star}}{\chi_{\parallel}\Delta t} = b_{y,i,j+1/2}^{2} \frac{T_{i,j+1}^{n+1} - T_{i,j}^{n+1}}{\Delta y^{2}} - b_{y,i,j-1/2}^{2} \frac{T_{i,j-1/2}^{n+1} - T_{i,j-1}^{n+1}}{\Delta y^{2}} + \frac{b_{y,i,j+1/2}b_{x,i,j+1/2}}{\Delta x\Delta y} \overline{\Delta T}_{i,j+1/2}^{\star} - \frac{b_{y,i,j-1/2,j}b_{x,i,j-1/2,j}}{\Delta x\Delta y} \overline{\Delta T}_{i,j-1/2,j}^{\star},$$

this requires solving a tridiagonal matrix (O[N]): simply use LAPACK

Does implicit work?

indeed it does; here, T_{hot}=10, T_{cold}=0.1

Does implicit work?

A real application: TI

initially small density perturbations with global thermal balance overdense regions cool and underdense are heated

Parallel implementation

the implicit method is not yet parallel

parallelization strategy is clear but work needs to be done

another approach is to use parallel iterative packages like PETSc

$$T \xrightarrow[\nu \to 0]{\lambda_{\max}} N^2 \Delta t_{\exp}$$

factor of N speed-up!

SUPER-TIME-STEPPING ACCELERATION OF EXPLICIT SCHEMES FOR PARABOLIC PROBLEMS

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$$\tau_{j} = \Delta t_{expl} \left((-1 + \nu) \cos\left(\frac{2j - 1}{N} \frac{\pi}{2}\right) + 1 + \nu \right)^{-1} \qquad j = 1, \dots N$$

$$\Delta t_{expl} = 2/\lambda_{max} \qquad \text{stability parameter } <<1$$

$$T = \sum_{j=1}^{N} \tau_j = \Delta t_{\text{expl}} \frac{N}{2\sqrt{\nu}} \left(\frac{(1+\sqrt{\nu})^{2N} - (1-\sqrt{\nu})^{2N}}{(1+\sqrt{\nu})^{2N} + (1-\sqrt{\nu})^{2N}} \right)$$

super timestep

prescription based on enforcing $p_N(\lambda)$ to be Chebyshev polynomial with [argument] < 1

Chebyshev vs Legendre

Comparison of $T_n(x) \& P_n(x)$: since |P| < 1 in (-1,1) = > better stability

Stabilized Runge-Kutta (RK)

A stabilized Runge–Kutta–Legendre method for explicit super-time-stepping of parabolic and mixed equations

[JCP, 2014]

Chad D. Meyer^{a,*}, Dinshaw S. Balsara^a, Tariq D. Aslam^b

typically multiple stages in RK introduced for higher accuracy here it is for stability with as long a timestep as possible

$$\frac{du}{dt} = \mathbf{M}u(t) \qquad u(t) = e^{t\mathbf{M}}u(0) \approx \left(1 + t\mathbf{M} + \frac{1}{2}(t\mathbf{M})^2 + \cdots\right)u(0)$$

analytic solution Taylor series expansion

 $R_s(z) = a_s + b_s P_s(w_0 + w_1 z)$ stability polynomial for s-stage RKL, $z = \lambda T$ for first order accuracy: $R_s(0) = 1$, $R'_s(0) = 1$, $= P_j \left(1 + \frac{2}{s^2 + s}z\right)u^n$

RKL1

first order Runge-Kutta Legendre scheme:

RKL1

compare with LP's recursion relations growth polynomial at each time substep matched to P_j

$$(j)P_j(x) = (2j-1)xP_{j-1}(x) - (j-1)P_{j-2}(x)$$

$$Y_{j} = \mu_{j}Y_{j-1} + \nu_{j}Y_{j-2} + \tilde{\mu}_{j}\tau \mathbf{M}Y_{j-1}; \quad 2 \leq j \leq s$$
$$u(t + \tau) = Y_{s}$$

$$\tilde{\mu}_j = \frac{2j-1}{j} \frac{2}{s^2+s}$$

similar schemes for RKL2, RKC1, RKC2

Comparison on ring diffusion AAG STS, v=0.01 for N=5, 10, 20; blows up for 50

RKL1; ok up to N=20; inaccurate beyond that

Conclusions

- anisotropic diffusion important in plasmas
- monotonicity, extrema-preservation
- Limiters can maintain extrema
- implicit scheme; parallelization is difficult
- super-time-stepping: AAG, RKC, RKL

Thank You!

References

- Sharma & Hammett 2007: extrema problem, limiters
- Sharma & Hammett 2011: semi-implicit scheme, tridiagonal, large speed-up
- Alexiades, Amiez & Gremaud 1996: super-time-stepping
- Verweer, Hundsdorfer & Sommeijer 1990: RKC
- Meyer, Balsara & Aslam 2014: RKL