

- Importance Sampling and Statistical mechanics.
- Markov Chain Monte Carlo.
- Simulated Annealing

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- We can take the approach that we will calculate the sum via Monte Carlo (random sampling). In that case, we will chose N random states, $k = 1 \dots N$ and calculate:

$$\langle X \rangle \simeq \frac{\sum_{k=1}^N X_k P(E_k)}{\sum_{k=1}^N P(E_k)}$$

The denominator is needed to normalize the weighted average correctly..

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- But this is ideally suited for importance sampling!

Importance Sampling and Statistical Mechanics

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- Making the particular choice $g_i = X_i P(E_i)/w_i$:

$$\left\langle \frac{X_i P(E_i)}{w_i} \right\rangle_w = \frac{\sum_i X_i P(E_i)}{\sum_i w_i} = \frac{\langle X \rangle}{\sum_i w_i}$$

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- Then:

$$\langle X \rangle = \left\langle \frac{X_i P(E_i)}{w_i} \right\rangle_w \sum_i w_i$$

- We can evaluate this expression approximately by selecting a set of N sample states randomly but non-uniformly such that the probability of choosing a state i is:

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- In this case, we get:

$$\langle X \rangle \simeq \frac{1}{N} \sum_{k=1}^N \frac{X_k P(E_k)}{w_k} \sum_i w_i$$

Note that the first sum is only over the states that we sample, but the second sum is over all states i and has to be calculated analytically!

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- In other words, we just choose N states in proportion to their Boltzmann probabilities and take the average of X over them..
- Unfortunately, we are not done yet – The catch is that it is not easy to pick states with probability $P(E_i)$. This is because to calculate $P(E_i)$, we need to know the partition function, Z .

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- Consider a single step in the process – Suppose that the previous state for the step before this one, was state i .
- For the new state, instead of choosing randomly, we will make some change (usually small) to the state i so as to create a new state.
- The choice of the new state is determined probabilistically by a set of transition probabilities T_{ij} that give the probability of changing from state i to j .

- If we choose T_{ij} correctly, we can arrange that the probability of visiting any particular state on any step of the Markov chain to be precisely the Boltzmann probability, $P(E_i)$.

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- When we take many steps and generate the entire chain, the complete set of states that we move through is a correct sample of the Boltzmann distribution and we can average any quantity we like over these states.

- The trick lies in choosing T_{ij} :

$$\sum_j T_{ij} = 1$$

and also

$$\frac{T_{ij}}{T_{ji}} = \frac{P(E_j)}{P(E_i)} = \frac{e^{-\beta E_j}/Z}{e^{-\beta E_i}/Z} = e^{-\beta(E_j - E_i)}$$

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- The Boltzmann distribution is a fixed point of the Markov chain.

Metropolis algorithm

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- We will accept or reject the new state with probability P_a :

$$P_a = \begin{cases} 1 & \text{if } E_j \leq E_i, \\ e^{-\beta(E_j - E_i)} & \text{if } E_j > E_i \end{cases}$$

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- This scheme will satisfy all the criterion of the transition probability: $\frac{T_{ij}}{T_{ji}} = e^{-\beta(E_i - E_j)}$

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- 6 Go to step 2.

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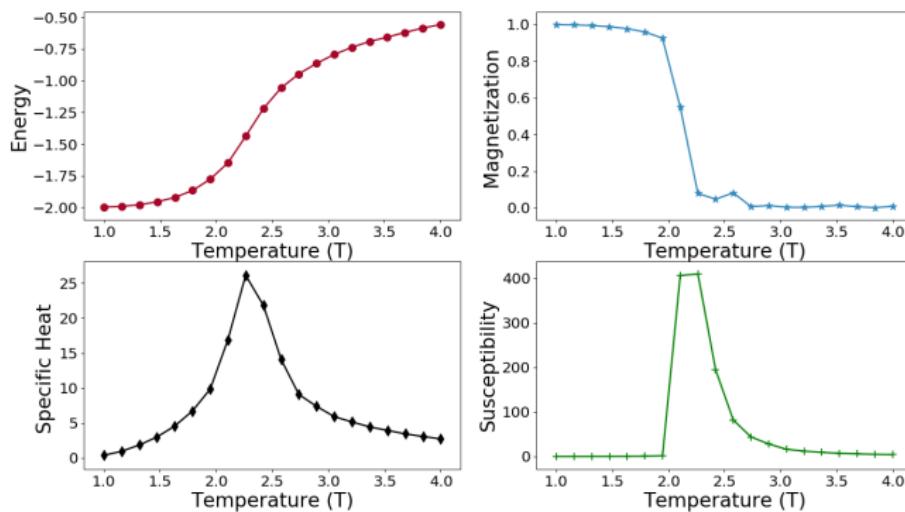
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- One has to choose a move set such that every possible state is reachable.
- That the Markov chain will go to Boltzmann distribution is proved but, how long will it take to reach equilibrium is not known.

Ising Model

$$E = - \sum_{\langle ij \rangle} s_i s_j$$



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- This in this limit:

$$P(E_i) = \begin{cases} 1 & \text{for } E_i = 0 \\ 0 & \text{for } E_i > 0 \end{cases}$$

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- As one lowers the temperature, the system should land in the ground-state!